

An Introduction to C++

Inheritance
Exceptions
A C++ review: from modular to generic programming

Inheritance

- ◆ is another very important feature
- ◆ it models the concept:
objects of type B are the same as A, but in addition have...
- ◆ Examples
 - ◆ A shape is a 2D figure which has an area and can be drawn, although I know neither generally
 - ◆ A triangle is a shape, but its area is ... and it looks like ...
 - ◆ A square is a shape, but its area is ... and it looks like ...
 - ◆ A complex figure is a shape and consists of an array of shapes

 - ◆ A monoid is a semigroup, but in addition contains a unit element
 - ◆ A group is a monoid, but in addition has an inverse

 - ◆ A simulation can be run but I don't know how generally
 - ◆ A Penna simulation is run this way ...

Abstract base classes

- ◆ are good for expressing common ideas
- ◆ We want to have a function that can run a simulation and print some information:
 - ◆

```
void perform(Simulation& s) {
    std::cout << "Running the simulation "
              << s.name() << "\n";
    s.run(); // run it
}
```
- ◆ This class must have an `name()` and a `run()` member function
 - ◆

```
class Simulation{
public:
    Simulation () {};
    virtual std::string name() const =0;
    virtual void run() =0;
};
```
 - ◆ `virtual` means that this function depends on concrete simulation
 - ◆ `=0` means that this function **must** be provided for any concrete simulation

Concrete derived classes

- ◆ PennaSim and IsingSim are both Simulations:
 - ◆

```
class PennaSim: public Simulation {
public:
    std::string name() const;
    void run();
};
```
 - ◆

```
class IsingSim: public Simulation{
public:
    std::string name() const;
    void run()
};
```
- ◆ Examples
 - ◆

```
Simulation x;
```

 // Error since it is abstract! `name()` and `run()` not defined
 - ◆

```
PennaSim p; // OK!
```
 - ◆

```
IsingSim i; // OK!
```
 - ◆

```
Simulation& sim=p; // also OK, since it is a reference!
```

Using inheritance

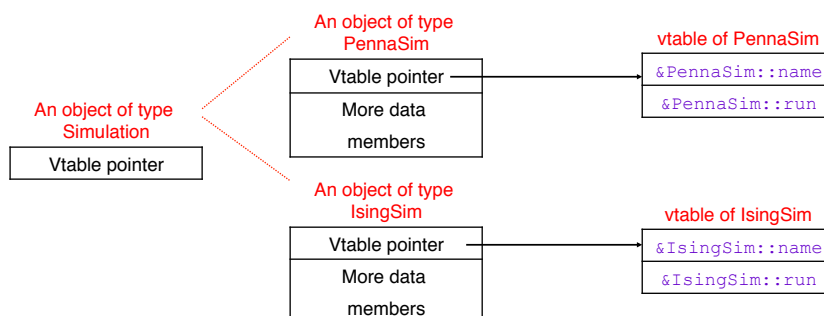
- ◆ recall the function `void perform(Simulation&);`
- ◆ let us call it for two simulations

```
PennaSim p;
IsingSim i;
perform(p); // will use PennaSim::name() and PennaSim::run()
perform(i); // will use IsingSim::name() and IsingSim::run()
```

- ◆ All virtual function can be redefined by derived class
- ◆ In addition a derived class can define additional members
- ◆ There exists a third access specifier: `protected`
 - ◆ means `public` for derived classes
 - ◆ means `private` for others

The virtual function table

- ◆ How does the program know the concrete type of an object?
 - ◆ The compiler creates a virtual function table (vtable) for each class
 - ◆ The table contains pointers to the functions
 - ◆ A pointer to that table is stored in the object, before the other members
 - ◆ The program checks the virtual function table of the object for the address of the function to call
 - ◆ Needs two memory accesses and cannot be inlined



Using templates instead

◆ The same could be done with templates:

```
◆ template <class SIMULATION>
  void perform(SIMULATION& s) {
    std::cout << s.name() << "\n";
    s.run();
  }
◆ class PennaSim {
  public:
    std::string name() const;
    void run();
};
◆ PennaSim p;
  perform(p); // instantiates the template for PennaSim
```

◆ But type of `SIMULATION` must be known at compile time!

Comparing virtual functions and templates

◆ Object Oriented Programming:

```
◆ void perform(Simulation& s)
  {
    s.run();
  }
```

- ◆ Object needs to be derived from Simulation
- ◆ Concrete type decided at runtime

◆ Generic programming:

```
◆ template <class SIM> void perform(SIM& s)
  {
    s.run();
  }
```

- ◆ Object needs to have a run function
- ◆ Concrete type decided at compile time

Virtual functions versus templates

Object oriented programming

- ◆ uses virtual functions
- ◆ decision at run-time
- ◆ works for objects derived from the common base
- ◆ one function created for the base class -> **saves space**
- ◆ virtual function call needs lookup in type table -> **slower**
- ◆ extension possible using only definition of base class
- ◆ Most useful for application frameworks, user interfaces, “big” functions

Generic programming

- ◆ uses templates
- ◆ decision at compile-time
- ◆ works for objects having the right members
- ◆ a new function created for each class used -> **more space**
- ◆ no virtual function call, can be inlined -> **faster**
- ◆ extension needs definitions and implementations of all functions
- ◆ useful for small, low level constructs, small fast functions and generic algorithms

When to use which?

- ◆ Generic programming allows inlining
 - ◆ faster code
- ◆ Object oriented programming more flexible
 - ◆ how to age an Array of animals of different types?

```
void show(std::vector<Animal*> a) {
    for (int i=0; i<a.size(); ++i)
        a[i]->grow();
}
```

- ◆ This works for array of mixed animals, e.g. fish, sheep, ...

Example: random number generators

- ◆ We want to be able to switch random number generators at runtime: use virtual functions
- ◆ First attempt: rng1.h
 - ◆ Make `operator()` a virtual function
 - ◆ Problem: virtual function calls are slow
- ◆ Second attempt: rng2.h
 - ◆ Store a buffer of random numbers
 - ◆ `operator()` uses numbers from that buffer
 - ◆ Only when buffer is used up, a virtual function `fill_buffer()` is called to create many random numbers
 - ◆ This reduces the cost of inheritance since the virtual function is called only rarely

Example: Penna model with fishing

- ◆ The Penna population class was:
 - ◆

```
class Population {
  ... constructors and more ...
  void simulate(int years); // the full simulation
  void step(); // one year
}
```
 - ◆

```
void Population::simulate(int years)
{
  while (years-->0)
    step();
}
```
 - ◆

```
void Population::step()
{
  ... lots of work to do one year ...
}
```

Example: Penna with fishing (part 2)

- ◆ Now we want to do a new simulation with fishing

- ◆ We want to reuse code and not copy&paste

```
◆ class FishingPopulation : public Population
{
    ... constructors ...
    void step(); // one year
}
```

```
◆ void FishingPopulation::step()
{
    Population::step(); // do the normal aging
    ... then implement fishing ...
}
```

Example: Penna with fishing (part 3)

- ◆ This will not do what we want since `Population::simulate` does not call the `step` function of `FishingPopulation`

```
◆ void Population::simulate(int years)
{
    while (years-- > 0)
        step();
}
```

- ◆ Solution: need to make `step()` a virtual function

```
◆ class Population {
    ... constructors and more ...
    void simulate(int years); // the full simulation
    virtual void step(); // one year
}
```

How to deal with runtime errors?

- ◆ What should our integration library do if the user passes an illegal argument?
 - ◆ Return 0?
 - ◆ Return infinity?
 - ◆ Abort?
 - ◆ Set an error flag?

- ◆ Neither of these is ideal
 - ◆ Return values of 0 or infinity cannot be distinguished from good results
 - ◆ Aborting the program is no good idea for mission critical programs
 - ◆ Error flags are rarely checked by the users

- ◆ Solution
 - ◆ C++ exception handling

C++ Exceptions

- ◆ The solution are exceptions

- ◆ The library recognizes an error or other exceptional situation.
 - ◆ It does not know how to deal with it
 - ◆ Thus it *throws* an exception

- ◆ The calling program might be able to deal with the exception
 - ◆ It can *catch* the exception and do whatever is necessary

- ◆ If an exception is not caught
 - ◆ The program terminates

How to throw an exception

- ◆ What is an exception?
 - ◆ An object of any type
- ◆ Thrown using the `throw` keyword:
 - ◆

```
if(n<=0)
    throw "n too small";
```
 - ◆

```
if(index >= size())
    throw std::range_error("index");
```
- ◆ Throwing the exception
 - ◆ causes the normal execution to terminate
 - ◆ The call stack is unwound, the functions are exited, all local objects destroyed
 - ◆ Until a catch clause is found

The standard exception base class

- ◆ Is in the header `<exception>`
 - ◆

```
class exception {
public:
    exception() throw();
    exception(const exception&) throw();
    exception& operator=(const exception&) throw();
    virtual ~exception() throw();
    virtual const char* what() const throw();
};
```
- ◆ The function qualifier `throw()` indicates that these functions do not throw any exceptions

The standard exceptions

- ◆ are in `<stdexcept>`, all derived from `std::exception`
- ◆ Logic errors (base class `std::logic_error`)
 - ◆ `domain_error`: value outside the domain of the variable
 - ◆ `invalid_argument`: argument is invalid
 - ◆ `length_error`: size too big
 - ◆ `out_of_range`: argument has invalid value
- ◆ Runtime errors (base class `std::runtime_error`)
 - ◆ `range_error`: an invalid value occurred as part of a calculation
 - ◆ `overflow_error`: a value got too large
 - ◆ `underflow_error`: a value got too small
- ◆ All take a string as argument in the constructor

Catching exceptions

- ◆ Statements that might throw an exception are put into a `try` block
- ◆ After it `catch()` clauses can catch some or all exceptions
- ◆ Example:

```
◆ int main()
  {
    try {
      std::cout << integrate(sin,0,10,1000);
    }
    catch (std::exception& e) {
      std::cerr << "Error: " << e.what() << "\n";
    }
    catch(...) { // catch all other exceptions
      std::cerr << "A fatal error occurred.\n";
    }
  }
}
```

Exceptions example: main.C, simpson.h, simpson.C

```

◆ int main() {
    bool done;
    do {
        done = true;
        try {
            double a,b;
            unsigned int n;
            std::cin >> a >> b >> n;
            std::cout << simpson(sin,a,b,n);
        }
        catch (std::range_error& e) {
            // also catches derived exceptions
            std::cerr << "Range error: " << e.what() << "\n";
            done=false;
        }
        // all other exceptions go uncaught
    } while (!done);
}

```

More exception details

- ◆ Exceptions and inheritance
 - ◆ A `catch(ExceptionType& t)` clause also catches exceptions derived from `ExceptionType`
- ◆ Rethrowing exceptions
 - ◆ If a `catch()` clause decides it cannot deal with the exception it can rethrow it with `throw;`
- ◆ More details in text books
 - ◆ Uncaught exceptions
 - ◆ `throw()` qualifiers
 - ◆ Exceptions thrown while dealing with an exception
 - ◆ Exceptions in destructors
 - ◆ Can be very bad since the destructor is not called!

C++ review

- ◆ Stack class
 - ◆ procedural
 - ◆ modular
 - ◆ object oriented
 - ◆ generic

Procedural stack implementation: stack1.C

```
void push(double*& s, double v)    int main() {
{
    *s+=v;                          double stack[1000];
}                                    double* p=stack;

double pop(double *&s)             push(p,10.);
{
    return *--s;                    std::cout << pop(p) << "\n";
}                                    std::cout << pop(p) << "\n";
// error of popping below
// beginning goes undetected!
}
```

Modular stack implementation: stack2.C

```

namespace Stack {
    struct stack {
        double* s;
        double* p;
        int n;};

    void init(stack& s, int l) {
        s.s=new double[l];
        s.p=s;
        s.n=l;}

    void destroy(stack& s) {
        delete[] s.s;
    }

    void push(stack& s, double v) {
        if (s.p==s.s+s.n-1) throw
            std::runtime_error("overflow");
        *s.p++=v;
    }

    double pop(stack& s) {
        if (s.p==s.s) throw
            std::runtime_error("underflow");
        return *--s.p;
    }

    int main() {
        Stack::stack s;
        Stack::init(s,100); // must be called
        Stack::push(s,10.);
        Stack::pop(s);
        Stack::pop(s); // throws error
        Stack::destroy(s); // must be called
    }
}

```

Object oriented stack implementation: stack3.C

```

namespace Stack {
    class stack {
        double* s;
        double* p;
        int n;
    public:
        stack(int=1000); // like init
        ~stack(); // like destroy
        void push(double);
        double pop();
    };

    int main() {
        Stack::stack s(100);
        // initialization done automatically
        s.push(10.);
        std::cout << s.pop();
        // destruction done automatically
    }
}

```

Generic stack implementation: stack4.C

```
namespace Stack {
template <class T>
class stack {
    T* s;
    T* p;
    int n;
public:
    stack(int=1000); // like init
    ~stack(); // like destroy
    void push(T);
    T pop();
};

int main() {
    Stack::stack<double> s(100);
    // works for any type!
    s.push(1.3);
    cout << s.pop();
}
```

Summary of Programming Styles

- ◆ Procedural implementation
 - ◆ possible in all languages
- ◆ Modular implementation
 - ◆ allows transparent change in underlying data structure without breaking the user's program. E.g. we can add range checks
- ◆ Object oriented implementation
 - ◆ additionally makes sure that initialization and cleanup functions are called whenever needed
- ◆ Generic implementation
 - ◆ works for any data type

Review of the numerical integration exercise

- ◆ The numerical integration exercise demonstrates all four programming styles:
 - ◆ 1st part: **procedural programming**
 - ◆ 2nd part: **modular programming**
 - ◆ We built a library
 - ◆ 3rd part **generic programming**
 - ◆ We uses templates
 - ◆ 4th part: **object oriented programming**
 - ◆ We derive from a base class

- ◆ After you have coded all four versions, perform benchmarks
 - ◆ Which version is fastest?
 - ◆ Which version is the most flexible?

Procedural programming

- ◆

```
double integrate( double (*f) (double),
                  double a, double b, unsigned int N)
{
    double result=0;
    double x=a;
    double dx=(b-a)/N;
    for (unsigned int i=0; i<N; ++i, x+=dx)
        result +=f(x);
    return result*dx;
}
```

- ◆

```
double func(double x) {return x*sin(x);}
cout << integrate(func,0,1,100);
```

- ◆ same as in C, Fortran, etc.

Generic programming

- ◆

```
template <class T, class F>
T integrate(F f, T a, T b, unsigned int N)
{
    T result=T(0);
    T x=a;
    T dx=(b-a)/N;
    for (unsigned int i=0; i<N; ++i, x+=dx)
        result +=f(x);
    return result*dx;
}
```
- ◆

```
struct func {
    double operator()(double x) { return x*sin(x); }
};
cout << integrate(func(),0.,1.,100);
```
- ◆ allows inlining!
- ◆ works for any type T

Object oriented programming

- ◆

```
Class Integrator { // base class implements integration
public:
    Integrator() {}
    double integrate(double a, double b, unsigned int n);
    virtual double f(double)=0;
};
```
- ◆

```
class MyFunc : public Integrator { // derived class
public:
    MyFunc() {}
    double f(double x) {return x*sin(x);} //implements function
};
```
- ◆

```
MyFunc f;
f.integrate(0,1,1000);
```